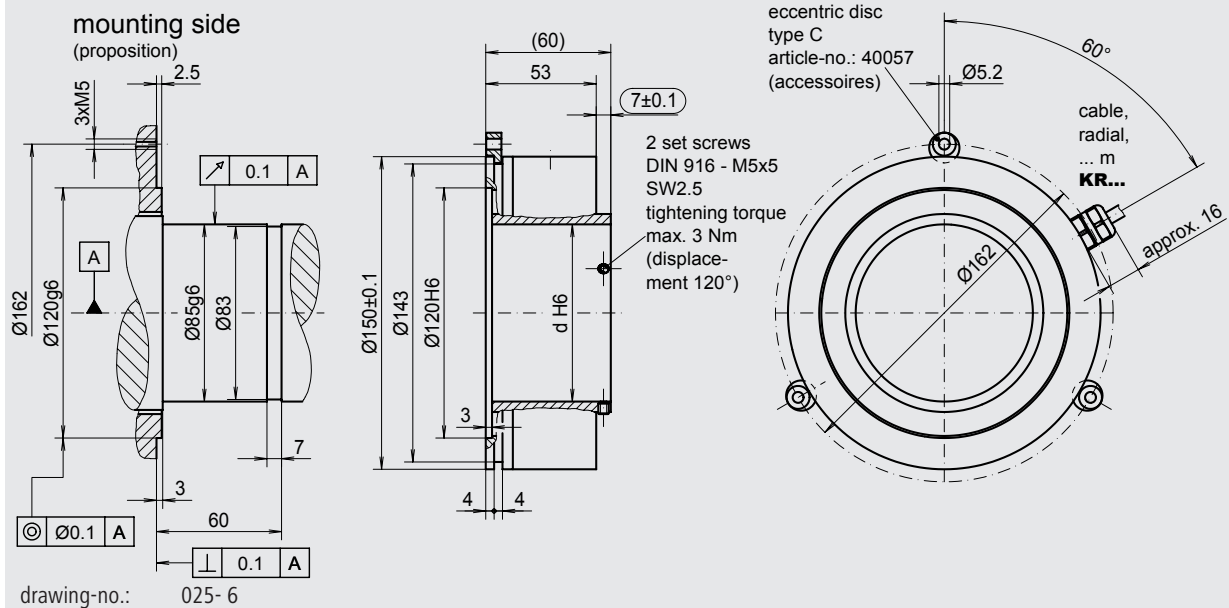


Incremental encoder without bearings



Features

- Incremental encoder with hollow shaft going through, without bearings
- Number of pulses up to 2500 pulses/rev.
- Centering seat $\text{Ø}120$ mm, mounting punch circle $\text{Ø}162$ mm
- TTL- or HTL- output signals
- Connector versions optional



Mechanical data

Design	A 4		A 4
Housing	aluminium, unpainted		
Protection	IP 54	according to DIN EN 60 529	IP54
Construction principle	OPSIC with slotdisc		
max. revolution (mechanical)	$n_{\max} \leq 3000 \text{ min}^{-1}$	(observe limit frequency)	
Permissible motor-shaft play	axial $\pm 0.2 \text{ mm}$ radial $\leq 0.2 \text{ mm}$		
Vibration	55... 2000 Hz $\leq 100 \text{ m/s}^2$	according to DIN IEC 60 068, part 2-6	
Shock	11 ms $\leq 1000 \text{ m/s}^2$	according to DIN IEC 60 068, part 2-27	
Hollow shaft diameter	d 85 mm	(standard), 60 mm to 85 mm possible	85
Weight	approx. 1500 g		

Electrical data

Number of pulses	Z	1000, 1024, 2048, 2500 pulses/rev.	XXXX
Electronic version (output signals)	TTL	Line driver-output stage, supply voltage: $U_B = 5 \text{ VDC} \pm 5 \%$ (polarity protected), output amplitude: $U_{LOW} \leq 0.5 \text{ V}$, $U_{HIGH} \geq 2.5 \text{ V}$	T
	HTL	Push pull-output stage (short-circuit proof), supply voltage: $U_B = 8 - 30 \text{ VDC}$ (polarity protected), output amplitude: $U_{LOW} \leq 1.5 \text{ V}$, $U_{HIGH} \geq U_B - 3 \text{ V}$	H
Output signals	A, B + Inv.	2 square wave pulse trains, electr. phase shifted 90° + signal inverting	BI
Limit frequency	f_G	120 kHz	
Output load current	I_{LOAD}	$\leq 70 \text{ mA}$	
Current consumption (no-load)	I_{max}	$\leq 100 \text{ mA}$	
Permissible cable length		$\leq 100 \text{ m}$ (Baumer Thalheim cable)	
Type of connection		cable, radial, 1.0 m (standard length)	KR1
Operating temperature range		$-20 \text{ }^\circ\text{C}$ to $+70 \text{ }^\circ\text{C}$	S
Permissible relative humidity		$\leq 90 \%$ (condensation not permitted)	

Options

Electronic version		TTL-output signals, line driver-output stage supply voltage: $U_B = 8 - 30 \text{ VDC}$ (polarity protected)	R
Output signals	A, B, N + Inv.	2 square wave pulse trains + zero pulse, electr. length 90° + signal inverting	NI
Type of connection	connector	performed at cable (ref. data sheet »Type of performed cables«)	...

Accessoires

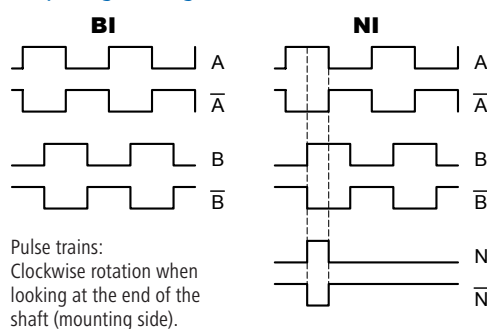
Eccentric disc type (3 pcs.)	article-no.: 40057
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Connection table

wire color	signals	wire color (old)
green	A	<i>brown</i>
brown	A inv.	<i>green</i>
grey	B	<i>grey</i>
black	B inv.	<i>pink</i>
pink	N	<i>red</i>
white	N inv.	<i>black</i>
red	+ U_B	<i>brown 0.5 mm²</i>
blue	0 V	<i>white 0.5 mm²</i>
yellow	+ U_{Sensor}	<i>blue</i>
violet	0 V_{Sensor}	<i>white</i>
transparent	shielding/housing	<i>transparent</i>

Old wire color until April 2008

Output signal diagram



Ordering example:

ITD 75 Incremental encoder ITD 75	A 4 Design A 4	Mechanical variant Y... = look at the drawing	2500 Number of pulses 2500 pulses/revolution	H Electronic version $U_B = 8 - 30 \text{ VDC HTL}$	BI Output signals A; B- track + inv.	KR1 Type of connection cable, radial, 1 m	S Operating temperature range $-20 \text{ }^\circ\text{C}$ to $+70 \text{ }^\circ\text{C}$	85 Hollow shaft diameter 85 mm	IP54 Protection IP54	Attachment kit variant
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